

(12) PATENT APPLICATION PUBLICATION

(21) Application No.202111014032 A

(19) INDIA

(22) Date of filing of Application :30/03/2021

(43) Publication Date : 17/02/2023

(54) Title of the invention : AUTOMATIC FENCE CLEANING DEVICE

(51) International classification :B05B0013000000,
G16H0050200000,
F24S0040200000,
E01H0001000000,
F28D0021000000

(31) Priority Document No :NA
(32) Priority Date :NA
(33) Name of priority country :NA
(86) International Application No :NA
Filing Date :NA
(87) International Publication No : NA
(61) Patent of Addition to Application Number:NA
Filing Date :NA
(62) Divisional to Application Number :NA
Filing Date :NA

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(57) Abstract :

A body 1 configured with motorized wheels 2 that assist in movement of the body 1, an Artificial intelligence (AI) enabled camera module 3 integrated with a microcontroller for detecting surrounding fences and proximity of the fences from the body 1 and other related parameters, wherein the microcontroller on processing signals generates a command to actuate the motorized wheels 2, a primary motorized sponge 4 linked with a first telescopic arm 5 for cleaning the fence, a second telescopic arm 6 connected to the first telescopic arm 5 via a ball joint assembly 7 that extends from the first arm 5 and proceeds towards another side of fence, a secondary motorized sponge 8 for cleaning another side of said fence, plurality of nozzles integrated within the first and second sponge 4,8 for dispensing cleaning agent on the fence, wherein the agent disperse through the sponges.

No. of Pages : 13 No. of Claims : 8